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LINE-SWEEP AMBIENT OBSCURANCE

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- I. SSAO and previous approaches
- 2. Our method
- 3. Results
- 4. Questions

I AMBIENT OCCLUSION

Is an approximation for global illumination



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Defined as the cosine-weighted hemisphere visibility



V is a binary visibility function (1 = hits geometry, 0 = does not hit geometry)

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Obscurance: Also account for the distance of the geometry

• Add a falloff term F that tapers off as a function of distance

• F(0) = I, F(inf) = 0

$$A(\mathbf{p}, \vec{n}) = \frac{1}{\pi} \int_{\Omega} F(D(\mathbf{p}, \vec{\omega})) \vec{n} \cdot \vec{\omega} d\vec{\omega}$$

Now need to know distance to occluder, D, instead

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Ideal solution

- · Ideally solved at each fragment, against all scene geometry
- Problem I: Dependent on scene complexity and scenes can get prohibitively large
- Problem 2: Generic geometry does not allow efficient acceleration
- Think about a path tracer that shoots hundreds of rays at each pixel: Too slow for real-time today

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- What can we afford, then?
- ~2000 clock cycles per pixel per frame, or ~60 bilinear texture fetches at most (assuming 1080p, 5ms/frame)

→ Screen-Space approximations of Ambient Obscurance

SCREEN-SPACE AMBIENT OBSCURANCE This is a depth map (dark = far, light = near)



The depth map represents incomplete scene geometry...

- Because we don't know what's behind the first depth layer
- Because we don't know what's outside the view frustum

• Oh well, can't have it all...:-(

So this is what SSAO does:

For the blue point...



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For the blue point...



Sample the surroundings...

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For the blue point...



Sample the surroundings...

So this is what SSAO does:

For the blue point...



Sample the surroundings...

So this is what SSAO does:

But pay attention to one sampling line.



So this is what SSAO does:

But pay attention to one sampling line..



All receivers along the line go through the same data!

Motivation

This gives rise to an idea:



Go through these points in one line sweep

The main idea

- We sweep through the line one step at a time
- We maintain an internal representation of the geometry along the line so far
- From this representation, we extract AO for each successive point



The internal data structure

- The internal data structure is a stack
- Holds a subset of the visited points
- Pop until the largest falloff-weighted occluder is at the top
- Evaluate AO from that occluder
- Push in the new point p and continue





Largest occluder

We only consider the largest occluder, but this is acceptable:



Largest occluder

All occluders

Time complexity

• Processing a line of N samples is O(N)



- Amortized constant cost O(I) per pixel per screen direction
- Previous methods, e.g. HBAO, takes multiple (say, 32) iterations for HQ

Reaching the final result

• Cover the whole framebuffer with lines...



Reaching the final result

Cover the whole framebuffer with lines...



• ...in multiple directions, and gather the results per screen pixel

3 RESULTS

1280(+256)×720(+144), GTX480

Our K = 16

HBAO K = 16, N = 48



3 RESULTS

1280(+256)×720(+144), GTX480

Our K = 16

HBAO K = 16, N = 32



2.56 ms

24.2 ms



Scaling

| Screen resolution | Our method | HBAO |
|-------------------|------------|---------|
| 800×600 | 1.49 ms | 10.5 ms |
| 1280×720 | 2.56 ms | 24.2 ms |
| 1920×1080 | 5.24 ms | 92.5 ms |
| 2560×1600 | 9.58 ms | 249 ms |



1920(+384)×1080(+216), 4.9ms/frame, GTX480

Line-Sweep Ambient Occlusion

4 QUESTIONS

Or comments...

