Scalable SSAO algorithms

Ville Timonen

SyysGraph 2013

CONTENTS

SSAO and previous approaches
Line-Sweep Ambient Obscurance (EGSR'13)
Far-Field Screen-Space Ambient Obscurance (HPG'13)
Questions

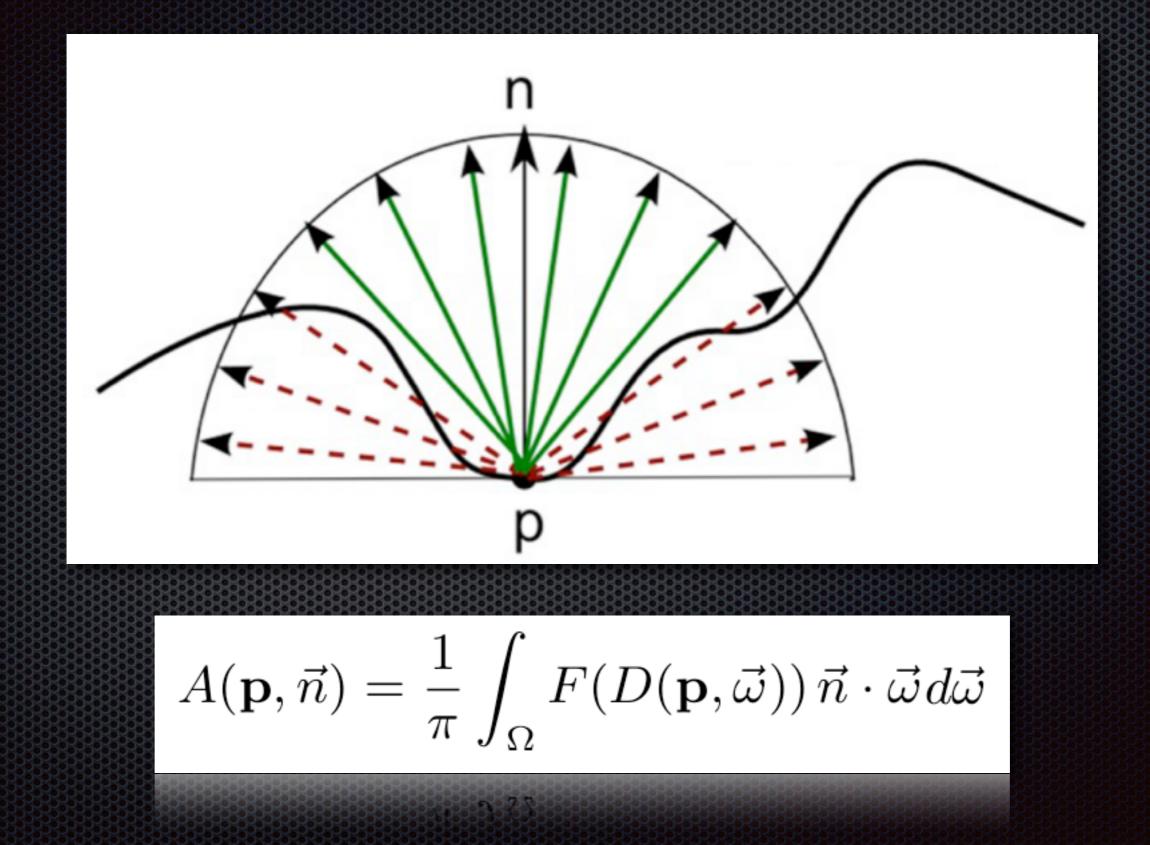
I AMBIENT OBSCURANCE

Is an approximation for global illumination



I AMBIENT OBSCURANCE

Defined as the cosine and falloff weighted hemisphere visibility

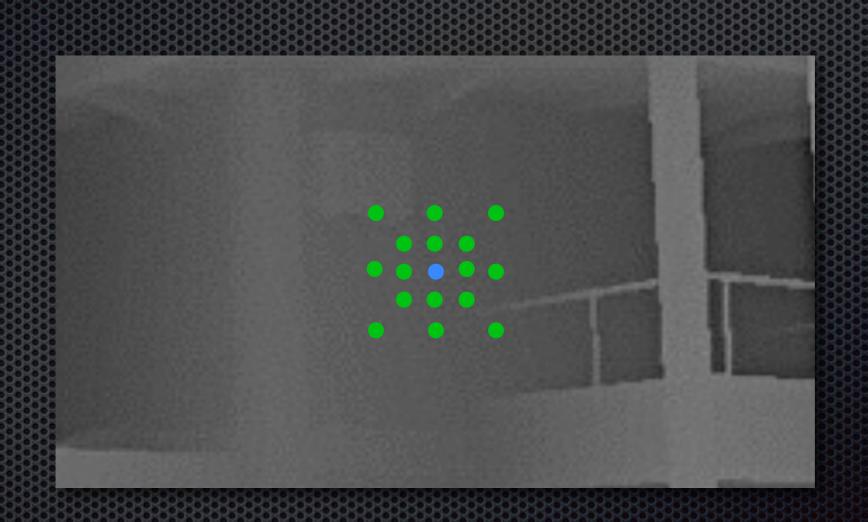


SCREEN-SPACE AMBIENT OBSCURANCE This is a depth map (dark = far, light = near)

A by-process of most graphics pipelines

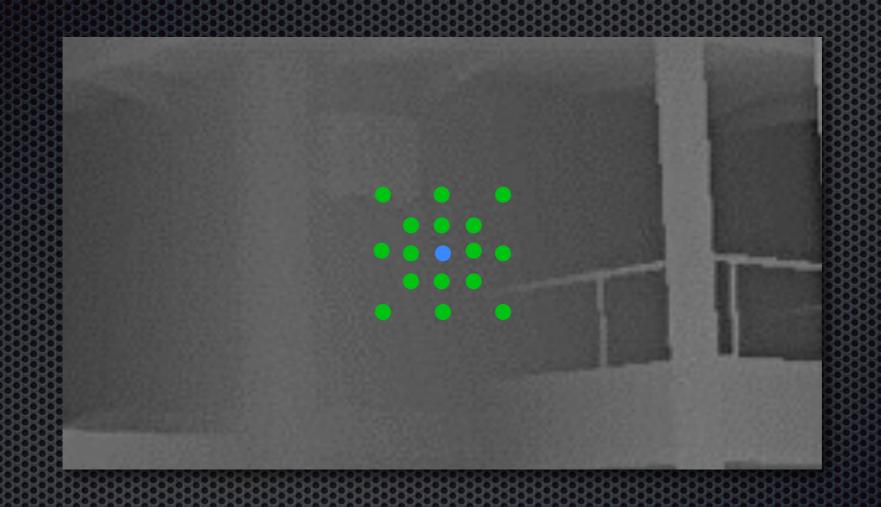
So this is what SSAO does:

For the blue point...



Sample the surroundings...

So this is what SSAO does:



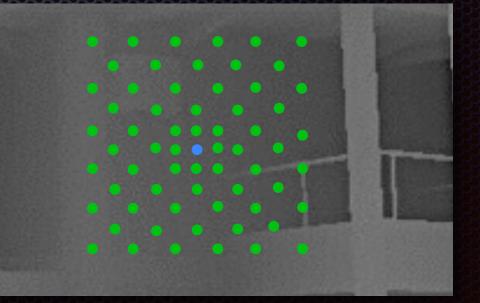
Deproject points into world space and evaluate AO:

$$A(\mathbf{p},\vec{n}) = \frac{1}{\pi} \int_{\Omega} F(D(\mathbf{p},\vec{\omega})) \, \vec{n} \cdot \vec{\omega} d\vec{\omega}$$

SCREEN-SPACE AMBIENT OBSCURANCE Traditional SSAO issues:

- The amount of sampling limits scalability
- Can be battled by:
 - Sparse sampling, which produces noise
 - Noise can be traded for blur, which corrupts details

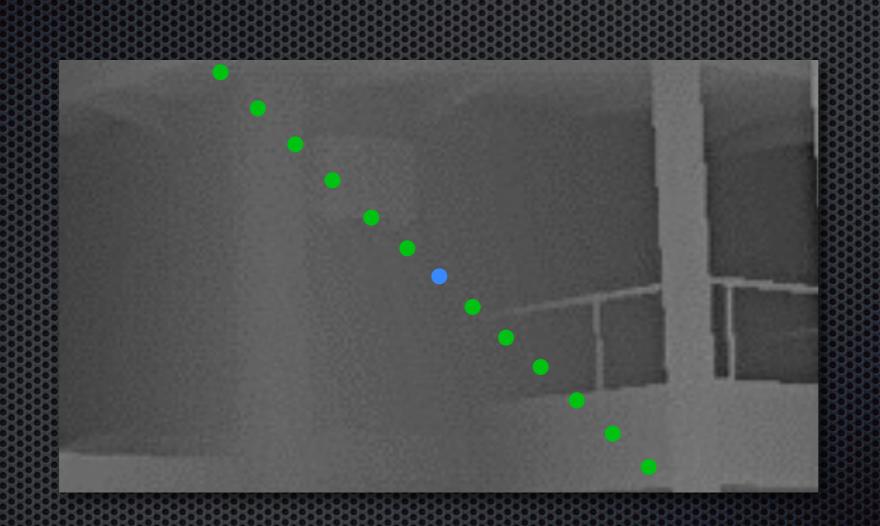
In any case, has trouble scaling beyond very local effects



Eurographics Symposium on Rendering 2013 Computer Graphics Forum 32(4) Best Student paper

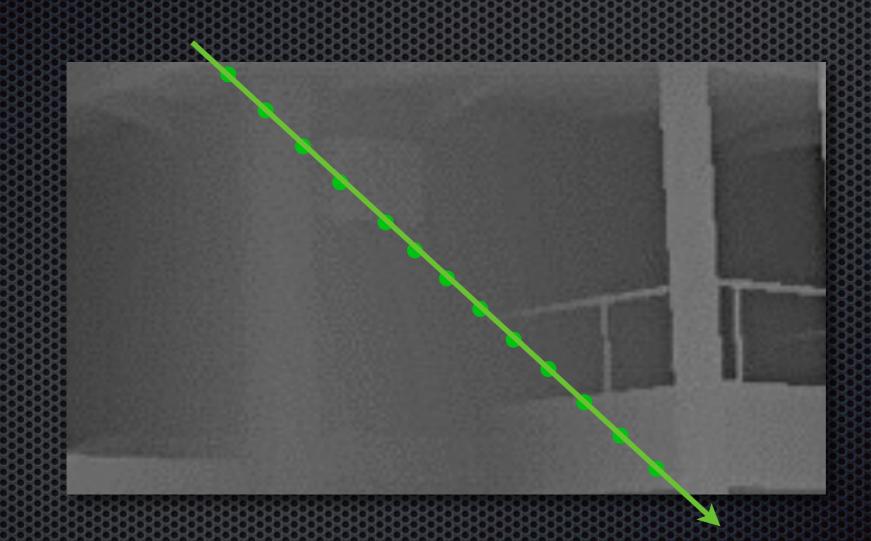
Ville Timonen

Consider samples along one line



All receivers along the line go through the same data!

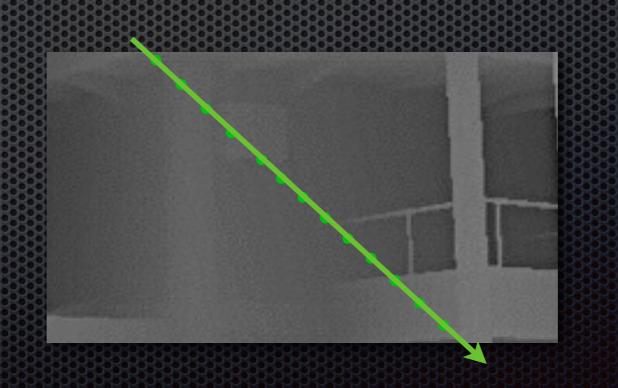
This gives rise to an idea:



Go through these points in one line sweep

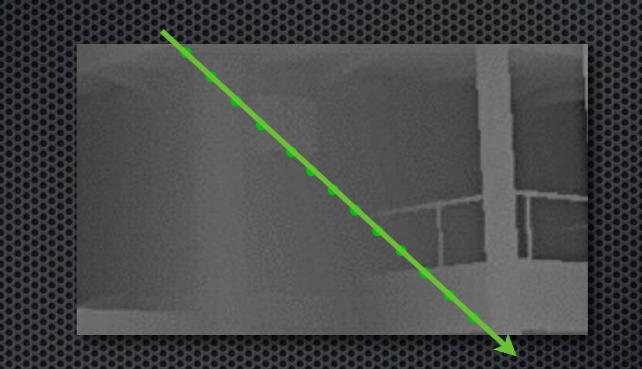
2 LINE SWEEP AMBIENT OBSCURANCE The main idea

- We sweep through the line one step at a time
- We maintain an internal representation of the geometry along the line so far: A stack of the visited points
- From this representation, we extract AO for each successive point



2 LINE SWEEP AMBIENT OBSCURANCE Time complexity

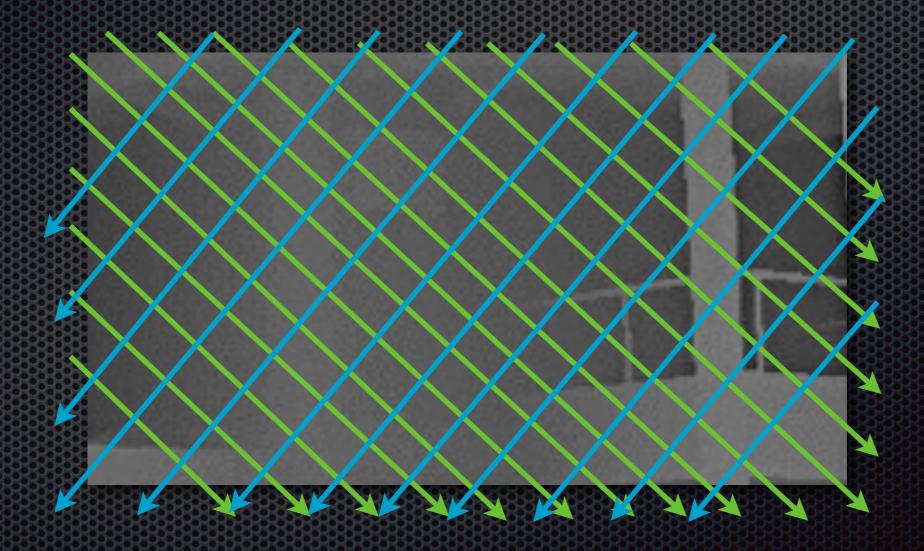
• Processing a line of N samples is O(N)



- Amortized constant cost O(1) per pixel per screen direction, unbounded range
- Previous methods, e.g. HBAO, takes multiple (say, 32) iterations for HQ

2 LINE SWEEP AMBIENT OBSCURANCE Reaching the final result

• Cover the whole framebuffer with lines...



• ...in multiple directions, and gather the results per screen pixel

2 LINE SWEEP AMBIENT OBSCURANCE 1280(+256)x720(+144)

GeForce GTX 480

Our K = 16

HBAO K = 16, N = 48



37.2 ms

2 LINE SWEEP AMBIENT OBSCURANCE 1280(+256)x720(+144)

GeForce GTX 480

Our K = 16



HBAO K = 16, N = 32



2.56 ms

24.2 ms

Scaling

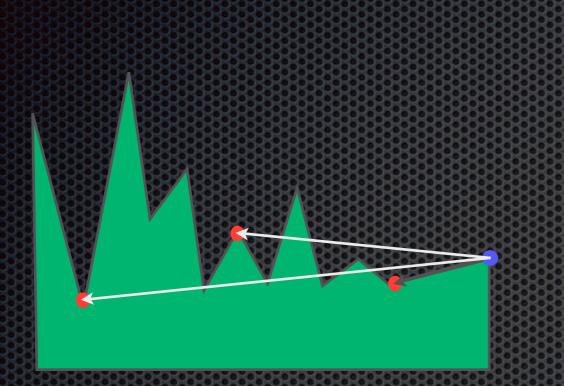
Screen resolution	Our method	HBAO
800×600	1.49 ms	10.5 ms
1280×720	2.56 ms	24.2 ms
1920×1080	5.24 ms	92.5 ms
2560×1600	9.58 ms	249 ms

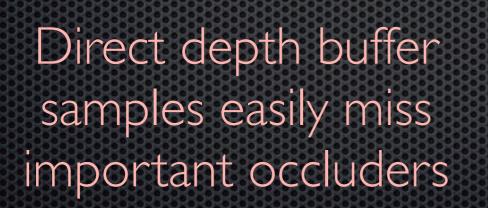
Line-Sweep Ambient Obscurance

High Performance Graphics 2013 Anaheim, California (ACM)

Ville Timonen

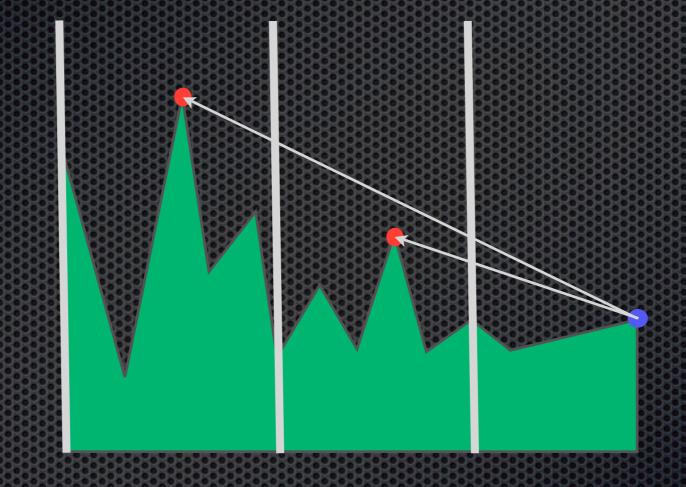
Previously used SSAO sampling strategies





Mip-mapping flattens the geometry, corrupts silhouettes

Our sampling strategy



We capture points important for AO

Our sampling strategy

Scans in multiple directions (one direction below)

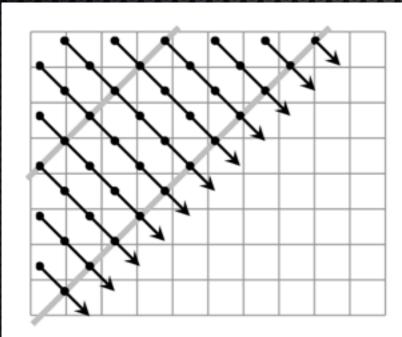


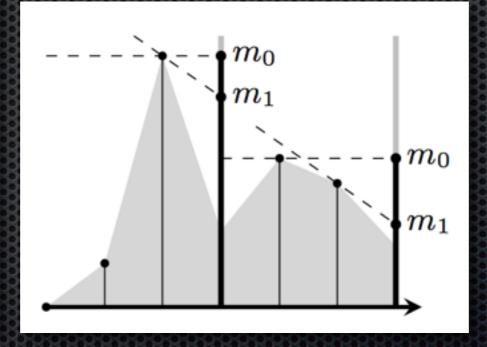


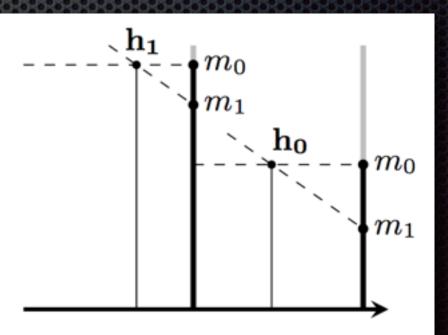


Find highest 'projections'' (m₀, m₁)

Construct final sample points h_i at the intersections

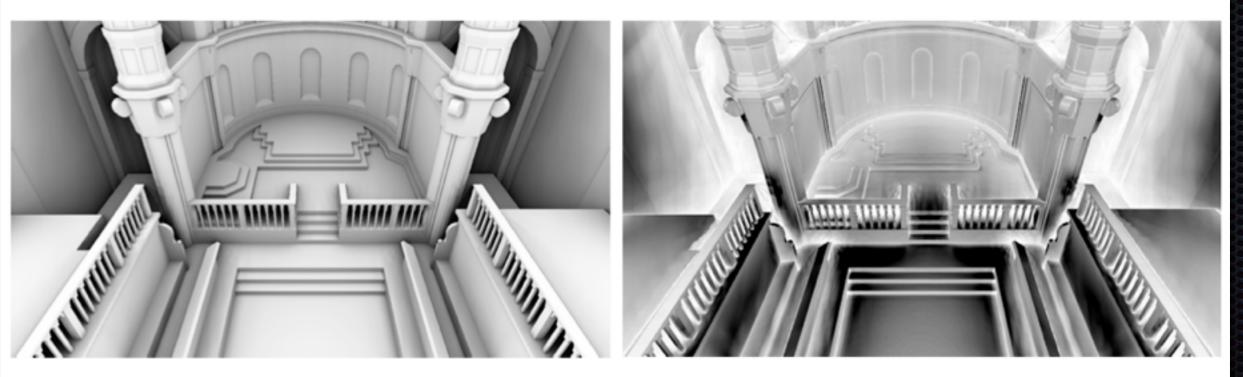






Results

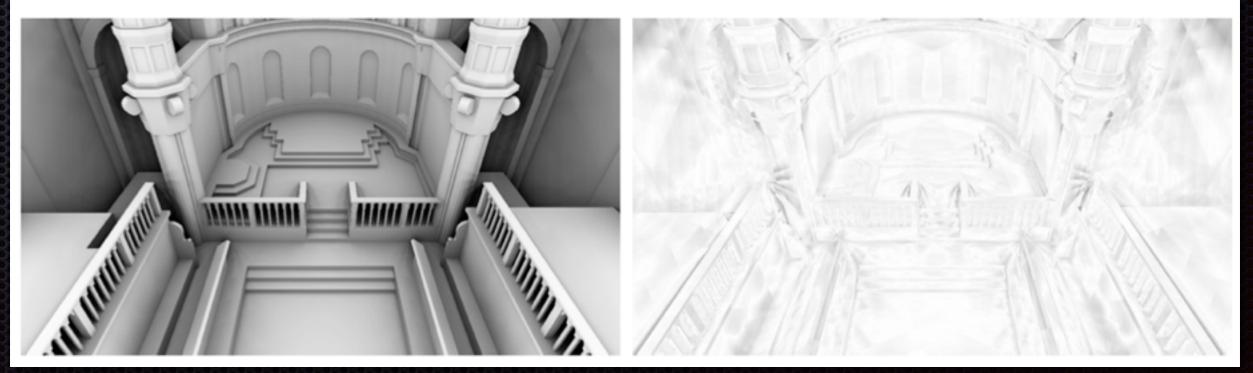
Mipmap K = 16



 $[P4] K = 8 \times 2$

 $\operatorname{error} \times 5$

 $\operatorname{error} \times 5$



Results

Our (4.6 ms) Radeon 7970

Ray traced (minutes)



Screen-Space Far-Field Ambient Obscurance

SUMMARY

2 LINE SWEEP AMBIENT OBSCURANCE Reduces time complexity from O(N)* to O(I) Fast SSAO results without undersampling artefacts

3 SCREEN-SPACE FAR-FIELD AMBIENT OBSCURANCE Typical multi-res complexity O(log(N))*, but considers the entire framebuffer at real-time framerates Results very close to a ray traced (screen-space) reference

*) Assuming a NxN framebuffer

5 QUESTIONS

Or comments...

